EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	sobot same colli$5.clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/03/14 17:27
L2	716	robot and colli$5.clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/03/14 17:32
L3	567	2 and ((measur$5 test$4 detect$4 determin$4 sens$4 identi$6 evaluat$5 estimat$5 transducer gauge cell monitor$4 comput$5 inspect$5 meter calculat$4)).clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33
L4	121	3 and compar$5.clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:30
L5	28	4 and (formula model mathematical equation expression).clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33
L6	95	4 and (formula model mathematical equation expression)	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:32
L7	3	6 and tolerance.clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33
L8	404	robot and (collision colliding collide).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/03/14 17:33
L9	131	(robot and (collision colliding collide)).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/03/14 17:33
L10	116	9 and ((measur$5 test$4 detect$4 determin$4 sens$4 identi$6 evaluat$5 estimat$5 transducer gauge cell monitor$4 comput$5 inspect$5 meter calculat$4)).clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33

L11	12	10 and (formula model mathematical equation expression).clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33
L12	1	11 and tolerance.clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/03/14 17:33